Teledyne RD Instruments

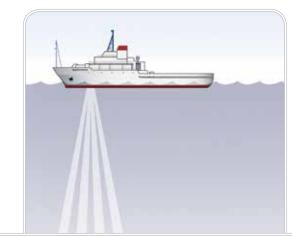
Ocean Surveyor

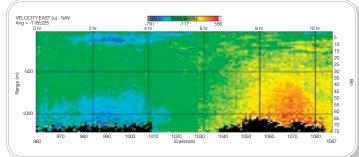
Vessel-Mount Long Range 3-D Current Profiling

Explore New Depths with Proven ADCP Technology

For over thirty years, Teledyne RD Instruments has been the preeminent supplier of Acoustic Doppler Current Profiling (ADCP) instrumentation for open ocean applications. Teledyne RDI's vessel-mounted OCEAN SURVEYOR family of ADCPs are the only instruments capable of collecting detailed maps of the distribution of water currents and suspended materials through the water column and along the ship's path—at depths and resolutions previously considered unattainable. In real time, the ADCP is also used to aid in situ decision-making, to adapt field operations, and to understand current regime characteristics.

Frequency	Range (m)	Cell Size (m)		
38kHz	800-1000	24		
75kHz	560-700	16		
150kHz	375-400	8		





PRODUCT FEATURES

- Versatile: Broadband signal processing combines with Narrowband processing to provide the ultimate in data versatility.
- Compact: Patented phased array transducers significantly reduce the transducer size and weight for ease of installation.
- Comprehensive: The Ocean Surveyor combines current profiling, backscatter profiling, and Doppler Velocity Log capability all within a single instrument.
- **Four-beam solution:** Patented 4-beam design provides increased data reliability and quality assurance.

Applications:

- Climate studies
- · Mid-ocean frontal mapping
- Fisheries research
- Deep-water cable-laying projects





Ocean Surveyor



Vessel-Mount Long Range 3-D Current Profiling

TECHNICAL SPECIFICATIONS

Water Profiling	Long Range Mode	38kHz		75kHz		150kHz				
	Vertical resolution cell size ¹	Max Range ²	Precision ³	Max Range ²	Precision ³	Max Range ²	Precision			
	4					325-350m	30cm/s			
	8			520-650m	30cm/s	375-400m	16cm/s			
	16 24	800-1000m 800-1000m	•	560-700m	16cm/s					
	High Precision Mode	38kHz		75kHz		150kHz				
	Vertical resolution cell size1	Max Range ²	Precision ³	Max Range ²	Precision ³	Max Range ²	Precision ³			
	4					200-250m	15cm/s			
	8			310-430m	15cm/s	220-275m	8cm/s			
	16 24	520-730m 730-780m	15cm/s 10cm/s	350-450m	7cm/s					
Profile Parameters	Velocity accuracy (typical) ±1.0% ± 0.5cm/s		cm/s	±1.0% ± 0.5cm/s			±1.0% ± 0.5cm/s			
	Velocity range	-5 to 9m/s		-5 to 9m/s		-5 to 9m/s				
	Number of depth cells Maximum ping rate	1-128 0.4kHz		1-128 0.7kHz		1-128 1.5kHz				
Bottom Track	Max altitude (precision <2cm/s)			950m		600m				
Dottom mack	Range Accuracy = <±2% actual			750111		ooom				
Echo Intensity Profile	Vertical resolution		Depth cell size, user configurable							
	Dynamic range Precision		80dB ±1.5dB							
Transducer and Hardware	Beam angle		30°							
	Configuration Communications		4-beam, phased array RS-232 or RS-422 hex-ASCII or binary output at 1200–115,200 baud							
System Power	AC input			AC, 47–63Hz						
	Power			1400W						
Software	Use TRDI's Windows™-based software for best results: VMDAS — Vessel-Mount Data Acquisition System; WinADCP —Data Display and Export, Velocity for advanced data processing									
Environmental	Operating temperature		-5° to 45°	С						
	Storage temperature		-30° to 60	-30° to 60°C						
Standard Sensors	Temperatures (mounted on transducer)		Range -5°	Range -5° to 45°C, Precision ±0.1°C, Resolution 0.03°						
System Components	• 38, 75, or 150kHz transducer									
	• 19" rack-mount electronic chassis									
	All-purpose deck box Gyrocompass interface board									
	LCD gyro offset control display									
	User to supply compass input or GPS navigation data and NMEA tilt information									
Dimensions	38kHz: 914.4mm dia.: 75kHz:	38kHz: 914.4mm dia.; 75kHz: 480mm dia.; 150kHz: 305mm dia. (line drawings available upon request)								
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- 1 Ranges at 1 to 5 knots ship speed are typical and vary with situation.
- 2 Single-ping standard deviation.
- 3 User's choice of depth cell size is not limited to the typical values specified.
- 4 Excludes errors introduced by changes in speed of sound profile, by tilting of transducer, and by slope of bottom.



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